

## PROJECT ADMINISTRATION DATA SHEET

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ORIGINAL

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REVISION NO. \_\_\_\_\_

Project No./(Center No.) E-25-603 (R6276-OAO)GTRC/~~GTX~~DATE 3 / 3 / 87Project Director: B.H. TongueSchool/~~KMX~~ MESponsor: U.S. Army Research OfficeAgreement No.: Grant No. DAAL03-87-G-0057Award Period: From 3/1/87 To 2/28/88 (Performance) 4/30/88 Reports

Sponsor Amount:

New With This ChangeTotal to Date

Contract Value: \$ \_\_\_\_\_

\$ 82,650

Funded: \$ \_\_\_\_\_

\$ 82,650

Cost Sharing No./(Center No.) \_\_\_\_\_ Cost Sharing: \$ \_\_\_\_\_

Title: Model Analysis Laboratory

## ADMINISTRATIVE DATA

OCA Contact John B. Schonk ext. 4820

1) Sponsor Technical Contact:

2) Sponsor Issuing Office:

Abram J. Van HallU.S. Army Research OfficeP.O. Box 12211Research Triangle Park, NC 27709

Military Security Classification: \_\_\_\_\_

ONR Resident Rep. is ACO: X Yes \_\_\_\_\_ No

(or) Company/Industrial Proprietary: \_\_\_\_\_

Defense Priority Rating: \_\_\_\_\_

## RESTRICTIONS

See Attached \_\_\_\_\_ Supplemental Information Sheet for Additional Requirements.

Travel: Foreign travel must have prior approval — Contact OCA in each case. Domestic travel requires sponsor approval where total will exceed greater of \$500 or 125% of approved proposal budget category.

Equipment: Title vests with GIT

## COMMENTS:

## COPIES TO:

SPONSOR'S I.D. NO. 02.102.001.86.020Project Director  
Research Administrative Network  
Research Property Management  
AccountingProcurement/GTRI Supply Services  
Research Security Services  
Contract Support Div.(OCA)(2)  
Research CommunicationsGTRC  
Library  
Project File  
Other

SPONSORED PROJECT TERMINATION/CLOSEOUT SHEETDate 4/8/88Project No. E-25-603-BSchool XXX MEIncludes Subproject No. (s) N/AProject Director(s) B. H. Tongue

GTRC/UIT

Sponsor U.S. Army Research OfficeTitle Model Analysis LaboratoryEffective Completion Date: 2/28/88 (Performance) 4/30/88 (Reports)

## Grant/Contract Closeout Actions Remaining:

☐ None☒ Final Invoice or Copy of Last Invoice Serving as Final☒ Release and Assignment☒ Final Report of Inventions and/or Subcontract:  
Patent and Subcontract Questionnaire  
sent to Project Director ☒☒ Govt. Property Inventory & Related Certificate☐ Classified Material Certificate☐ Other \_\_\_\_\_

Continues Project No. \_\_\_\_\_ Continued by Project No. \_\_\_\_\_

## COPIES TO:

Project Director  
Research Administrative Network  
Research Property Management  
Accounting  
Procurement/GTRI Supply Services  
Research Security Services  
Reports Coordinator (OCA)  
Program Administration Division  
Contract Support Division

Facilities Management - ERB  
Library  
GTRC  
Project File  
Other \_\_\_\_\_  
\_\_\_\_\_  
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**FINAL REPORT**  
**MODAL ANALYSIS LABORATORY**

Grant Number: DAAL03-87-G-0057

submitted to

U.S. Army Research Office  
Research Triangle Park, NC 27709-2211

submitted by

Benson H. Tongue  
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April 5, 1988

The main item of discussion in this report is the GenRad Computer-Aided Test System 2515, acquired through grant E25-603B. The following is a short account of the uses to which the equipment has been put.

The first task upon receiving the main unit was to determine if the operation was satisfactory. Upon testing, it was determined that the noise levels on several of the channels was too high. Subsequent study indicated a hardware defect which was repaired under warranty. After verification of the unit's abilities in deterministic testing, applications to experimental projects were begun.

The main task to date that the GenRad has been utilized for has been an experimental investigation of chaotic responses in a simple mechanical system. A single degree of freedom device has been constructed to model the dynamics of a periodically forced buckled beam. The actual mechanism is, in fact, a slider-crank mechanism. Thus the results of the experimental study will have a reasonably wide ranging significance, as it will demonstrate that complex nonlinear behavior can occur in fairly common mechanical systems. An analog transducer mounted on a pivot point of the mechanism produces a signal proportional to the angular position of one arm of the linkage. The signal is then passed through an R-C operational amplifier circuit to obtain the differentiated position measurement. This procedure produces real time angular position and angular velocity signals that are ready for data acquisition, the GenRad being utilized for this task. The system is equipped with a CRT screen for numerical and graphical data representation. The system also contains a floppy disk drive for data transfers and a hard disk drive for high-volume data storage.

The GenRad system contains a unique operating system that supports the the TSL-2 user programming language. The use of this language allows the system to sample the position and velocity signal, and assign them to separate data arrays, ready for further signal processing. Software capabilities of the unit are sufficient to allow on-board spectral analysis of the measurements and this capability is exploited in the current project. Internal graphics abilities, coupled with external hard copy devices, permit phase plane and time series representations of the data.

Programs were initially written to obtain time traces of the signals on the CRT screen. At this point, the system was configured to act as an oscilloscope with sampling and data storage capabilities. Based on the encouraging results from initial phases

of the research, the unit was used to investigate Poincaré sections of the nonlinear phase flow and generate spectral decompositions of the motion. The results indicate that subharmonic and chaotic regimes exist for the test device. Work is now ongoing in classifying the different regimes in which particular behavior types occur and in developing a match between the experimental results and numerical simulations.

It is planned that the graduate student currently working on this project, Mr. David Gregorson, will receive his Master's degree by December 1988. The results of his research will be submitted for publication in an appropriate archival journal.

In addition to the above work, research is being initiated that will utilize the GenRad 2515, along with appropriate vibrational transducers, to be used in parameter identification for light weight manipulator dynamics and controls studies. It is anticipated that the GenRad can be used for on-line modal identification.

The final area of current interest is in advanced modal analysis of structures. A methodology has been developed that allows very accurate analytical estimations of a system's natural frequencies with a very small number of assumed modes. The GenRad will be utilized along with appropriate vibration transducers to provide an experimental match to the analytical estimations, both for beam-like and plate-like structures.